

RS485 & 4-20mA Current pH Sensor **User Manual**

Product Model: S-pH-01

Version: V1.0







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1 Introduction

S-pH-01 soil PH sensor solves the shortcomings of traditional soil PH that need to be equipped with professional display instruments, cumbersome calibration, difficult integration, high power consumption, high price, and difficult to carry. Can be widely used in agricultural irrigation, flower gardening, grassland pasture, soil speed measurement, plant cultivation, scientific experiments and other fields. S-PH-01 consumes low power and provides long-term, uninterrupted monitoring.

Features:

- The new soil pH sensor realizes real-time monitoring of soil PH online.
- It adopts international advanced solid dielectric and large-area polytetrafluoroethylene liquid junction, which is not easy to block and maintenance-free.
- Waterproof and sealed, high integration, small size, low power consumption, easy to carry, can be used outdoors.
- High precision, fast response, good interchangeability and reliable performance.
- Complete protection circuit and multiple signal output interfaces are available.





2 Specifications

рН	
Range	0 to 14 pH
Accuracy	±0.1 pH
Resolution	0.01 pH
General Parameters	
Product Model	S-pH-01
Interface	RS-485
Protocol	MODBUS-RTU RS485
Power Supply	3.6 ~ 30V DC
Current Consumption	Max 6mA @24V DC
IP Rating	IP65
Cable Length	5 meters
Operating Temperature	-40 ~ 85 ℃
Installation	All buried or probe into all of the measured medium
Device Weight	400g





3 Wiring and Output

	RS485+/A/T+ RS485-/B/T- VCC+ VCC- Current Output				
Yellow	RS485+/A/T+				
White	RS485-/B/T-				
Red	VCC+, power supply				
Black	VCC-, power ground				
Blue	Current Output				
Sensor configuration para	meters such as Modbus address, baud rate, parity bit, communication				
protocol, etc. are stored in t	the EEPROM (Power Down Storage Device) inside the module. Sometimes				
the specific configuration o	f these parameters is forgotten and communication with the module is not				
possible. In order to prevent this problem, the module has a button. After pressing for three seconds,					
the internal indicator of the module is off. When the button is released, all parameters of the module are					
restored to the following factory settings:					
1. Modbus address is 1					
2. Communication configuration is 9600, N, 8, 1 (9600bps, no parity, 8 data bits, one stop bit)					
The communication protocol is Modbus-RTU					

Output Mode	Range	Calculation	
00		pH = 14 * (current value - 4) /16	
Current Output	рН: 0 ~ 14 рН	if current value=12mA,	
		pH = 14*(12-4)/16=7	
	рН: 0~ 14 рН	pH = pH register value / 100	
	Temperature: -40 ~80 °C	pH = temperature register value / 100	





4 Dimensions







5 Installation

5.1 Installation method

The sensor measures the pH of the water or the pH of the soil. When the sensor is shipped from the factory, the probe position has a transparent protective cover, and the built-in protective liquid protects the probe. When using it, please remove the protective cover first. Under normal circumstances, the pH value in the air is between 6.2 and 7.8.

When measuring the pH of the solution, the sensor has a 3/4 NPT pipe thread for fixed installation. When measuring the pH value of the soil, insert the probe part vertically into the soil. After burying the sensor, pour a certain amount of water around the soil to be tested, wait a few minutes, and wait until the water is immersed in the probe to read the data. Normal conditions Under the soil, the soil is neutral, the pH value is about 7, the soil in different places, the actual pH value will be different, it should be determined according to the actual situation.

5.2 Precautions

In order to ensure that the electrode correctly measures the pH value in the pipeline, it should avoid the occurrence of air bubbles between the measuring cells and cause data misalignment. Do not use live wiring. After the wiring is checked, it can be energized. Do not arbitrarily change the components or wires that have been soldered at the factory. The sensor is a precision device. Please do not disassemble it when using it. Touch the sensor surface with sharp objects or corrosive liquid to avoid damage to the product.

5.3 Maintenance

The input end of the instrument (measuring electrode socket) must be kept dry and clean to prevent dust and moisture from entering; avoid immersing the electrode in the protein solution and acidic fluoride solution for a long time to avoid contact with the silicone oil; after long-term use of the electrode, the electrode can be Soak the lower end in 4% HF solution (hydrofluoric acid) for 3~5 seconds, then wash it with distilled water, then soak it with 0.1mol/L hydrochloric acid to renew the electrode; in order to make the measurement more accurate, the electrode should be calibrated frequently. And cleaned with distilled water; the transmitter should be placed in a dry environment or control box to avoid leakage or measurement error caused by water droplets splashing or damp.





6 Modbus Communication Protocol

6.1 Serial communication parameters

Modbus is a serial communication protocol. It is the standard for communication instruments in a variety of instrumentation and smart sensors. It has a wide range of applications in smart sensors. The Modbus protocol is a master-slave architecture protocol. There is a master node, and other nodes that use the Modbus protocol to participate in communication are slave nodes. Each slave has a unique device address. The sensor has an RS485 interface and supports the Modbus protocol. The factory default value of communication parameters is: baud rate 9600bps, one start bit, 8 data bits, no parity, one stop bit. The communication protocol is the Modbus RTU protocol. The communication parameters can be changed by the setting program or Modbus command. After the communication parameters are changed, the sensor needs to be powered on again to take effect.





6.2 Modbus Register

Parameter	Register address	Modbus Parameter Type Function		Parameter range and description	Defaults	
			number			
Temperature value	00000 /0	INT16	0/4	-4000-8000 corresponds to -	N1/A	
TEMPRATURE	0x0000 /0	Read only	3/4	40.00~80.00 °C.	N/A	
PH value	0.0001 /4	UINT16	2//		N/A	
PHVALUE	0x0001 /1	Read only	3/4	0-1400 corresponds to 0.00-14.00		
PH calibration AD value	00000 /0	UINT16	2/4	-2000~2000 corresponds to -	N1/0	
PHCALIBRAWAD	0x000272	Read only	3/4	2000~2000	N/A	
Temperature compensation enable TEMPCOMPENSATEEN	0x0020 /32	UINT16 Read and write	3/6/16	0: Turn on temperaturecompensation1: Turn off temperaturecompensation	0	
PH calibration point 0				2000, 2000 corresponds to		
(pH = 4.01)	0x0030 /48	Bood and write	3/6/16	2000~2000 corresponds to -	N/A	
PHCALIBRAWAD0		Read and write		2000~2000		
PH calibration point 1		UINT16	3/6/16	-2000-2000 corresponds to -		
(pH = 7.00)	0x0031 /49			2000~2000 corresponds to	N/A	
PHCALIBRAWAD1				2000 2000		
PH calibration point 2		UINT16	3/6/16	-2000~2000 corresponds to -		
(pH = 10.01)	0x0032 /50	Read and write		2000~2000	N/A	
PHCALIBRAWAD2						
Modbus slave address	0x0200 /512	UINT16	3/6/16	0-255	1	
(ADDRESS)		Read and write				
				0-6		
				0:1200bps		
Serial communication		UINT16		1:2400bps	3:9600b	
baud rate (BAUDRATE)	0x0201 /513	Read and write	3/6/16	2:4800bps	ps	
				3:9600bps		
				4:19200bps		
				5:38400bps		
Serial communication	0x0202 /514	UINT16	3/6/16	0~1	0:	
protocol (PROTOCOL)		Read and write		0: Modbus RTU	Modbus	





				1: Modbus ASCII	RTU	
				0-2	0: No	
Serial communication	0x0203 /515		3/6/16		parity	
Check digit (PARITY)		Read and write				
				2: Odd parity		
Serial communication	0x0204 /516	UINT16	3/6/16		1: 8 data	
data bits (DATABITS)		Read and write		1: 8 data bits	bits	
Serial communication		UINT16		0-1	0: 1 stop	
stop bit (STOPBITS)	0x0205 /517	Read and write	3/6/16	0: 1 stop bit	bit	
				1:2 stop bit		
				0-250 corresponds to 0-2500		
				milliseconds		
Conicl communication		UINT16	Sx.	After the sensor receives the host		
Serial communication				request command, it delays for a		
delay response	0x0206 /518	Read and write	3/6/16	period of time and then responds.	0	
(RESPONSEDELAY)			2-1	The delay time is the set value *10		
				milliseconds. This feature is		
				disabled when set to 0.		
		\sim		0-250 corresponds to 0-250		
		$\mathcal{O}\mathcal{O}\mathcal{O}$		seconds		
Serial communication				The host does not require a request,		
active output time		UINT16		and the sensor automatically sends		
interval	0x0207 /519	Read and write	3/6/16	data at regular intervals. The time	0	
(ACTIVEOUTPUTINTER				interval is the set value *1 second.		
VAL)				This feature is disabled when set to		
				0.		
00						





6.3 Detail of Modbus Register

TEMPERATURE Temperature value					
Parameter range	Parameter range-4000 ~ 8000 corresponds to -40.00 ~ 80.00°CDefault: none				
Parameter storage	None				
Meaning: Temperatur	re measurement value, negative number is represented by	complement code.			
Example: If the return	ned value is 0702H (hexadecimal, original code), the first by	yte high byte is 07H,			
the second byte low I	byte is 02H, then the temperature measurement value is (0	7H*256+02H)			
/100=17.94 degrees Celsius.					
If the returned value is FF05H (hexadecimal, complement), the first byte high byte is FFH, the second					
byte low byte is 05H, then the temperature measurement value is ((FFH*256+05H)- FFFFH-1H)/100 =					
(FF05H-FFFFH-1H) / 100 = -2.51 degrees Celsius.					

PHVALUE PH value					
Parameter range	0-1400 corresponds to 0-14.00	Default: None			
Parameter storage	None				
Meaning: PH value					
Example: If the returned value is 02BCH (hexadecimal), the first byte high byte is 02H, the second					
byte low byte is BCH, then the measured value is (02H*256+BCH)/100=(2*256+188)/100					
=7.00. Represents a PH of 7.00					

PHCALIBRAWAD PH calibration AD value					
Parameter range-2000 ~ 2000 corresponds to -2000 ~ 2000Default: Not					
Parameter storage None					
Significance: The AD value is used for PH calibration.					
Example: If the returned value is 02BCH (hexadecimal), the first byte high byte is 02H, the second					
byte low byte is BCH, then the measured value is (02H*256+BCH)=(2* 256+188) =700.					

TEMPCOMPENSATEEN Temperature compensation enable				
Parameter range	0: Turn on temperature compensation	Default: None		
	1: Turn off temperature compensation			





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Parameter storage None

Meaning: PH temperature compensation is enabled.

PHCALIBRAWAD0 PH calibration point 0 (pH = 4.01)					
Parameter range	-2000~2000 corresponds to -2000~2000	Default: None			
Parameter storage	None				

Significance: Put the pH probe into the pH calibration AD value after stabilization in a standard buffer of pH = 4.01.

Example: If the returned value is FF24H (hexadecimal, 16-bit signed integer, negative number is represented by two's complement), the first byte high byte is FFH, the second byte low byte is 24H, then measurement The value is -(FFFFH-FF24H+1H)=-00DCH=-(00H*256+DCH)=-(0*256+220)=-220.

PHCALIBRAWAD1 PH calibration point 1 (pH = 7.00)					
Parameter range -2000~2000 corresponds to -2000~2000 Default: None					
Parameter storage	None				
Significance: Put the	pH probe into the pH calibration AD value after stabilization	n in a standard buffer			
of pH = 7.00.					
Example: If the returned value is 0000H (hexadecimal, 16-bit signed integer, negative number is					
represented by two's complement), the first byte high byte is 00H, the second byte low byte is 00H,					

then measurement The value is 0000H==(00H*256+00H)=(0*256+0) =0.

PHCALIBRAWAD2 PH calibration point 0 (pH = 7.01)			
Parameter range	-2000~2000 corresponds to -2000~2000	Default: None	
Parameter storage	None		
Significance: Put the pH probe into the pH calibration AD value after stabilization in a standard buffer			
of pH = 7.01.			
Example: If the returned value is 00DCH (hexadecimal, 16-bit signed integer, negative number is			
represented by two's complement), the first byte high byte is 00H, and the second byte low byte is			
DCH, then measurement The value is =(00H*256+DCH)=(0*256+220)=220.			





SLAVEADDR Modbus slave address		
Parameter range	0-255	Default: 1
Parameter storage	Store now	
Modbus address, can be set to 0-255. When the address dial switch external to the module is set to		
address 0, the contents of this register are used as the slave address. After the configuration, you		
need to power on again or use the RST command to restart the module to make this address take		
effect. Use this command to modify the module address without setting up the chassis.		

BAUDRATE Seria	I communication baud rate		
Parameter range	0-5		Default: 3
C C	0:1200bps		\sim
	1:2400bps		
	2:4800bps		
	3:9600bps		
	4:19200bps		
	5:38400bps		
Parameter storage	Store now	0	

PROTOCOL Serial communication protocol			
Parameter range	0~1	Default:0	
	0: Modbus RTU		
	1: Modbus ASCII		
Parameter storage	Store now		

PARITY Serial communication check digit		
Parameter range	0-2	Default:0
	0: No parity	
	1: Even parity	
	2: Odd parity	
Parameter storage	Store now	





DATABITS Serial communication data bit		
Parameter range	1 1: 8 data bits	Default:1, Only supports 8 data bits, others are invalid
Parameter storage	Store now	

STOPBITS Serial communication stop bit		
Parameter range	0-1	Default:0
	0: 1 stop bit	
	1:2 stop bit	\sim
Parameter storage	Store now	

RESPONSEDELAY Serial communication delay response			
Parameter range	0-255	Default:0	
Parameter storage	Store now		
The serial communication delay response is used when the host sends a request command, the			
module delays (RESPONSEDELAY*10) milliseconds, and then returns the response data to the host.			
For example, if RESPONSEDELAY=5 is set, then the module delays 5*10=50 ms to respond to the			
host request. When set to 0, it responds immediately without delay. This command is mainly used			
when the host is slow to switch from the RS485 transmission state to the receiving state.			

ACTIVEOUTPUTINTERVAL ---- Serial communication active output time intervalParameter range0-255Default:0Parameter storageStore nowDefault:0The serial communication active output time interval is used when the host does not need to send a
request command, the module actively outputs the response data, and the output interval is
ACTIVEOUTPUTINTERVAL seconds. For example, if ACTIVEOUTPUTINTERVAL=5 is set, the
module outputs data according to the set communication protocol every 5 seconds. When set to 0, the
active output is invalid, and the host can respond after receiving the request. This command is mainly
used in the case of wireless transmission such as GPRS, where the terminal note needs to send data
actively.

Note: When set to active output data, only one module can be connected to the RS485 bus to avoid bus data conflicts.

