

# Solid State Relays AQ-A RELAYS ( AC output type )

**Product Catalog** 

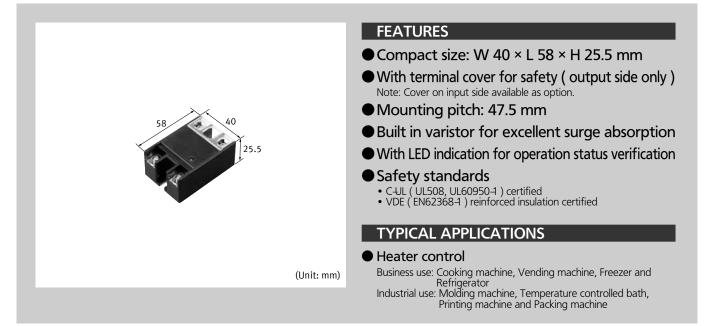
# IN Your Future

**Solid State Relays** 

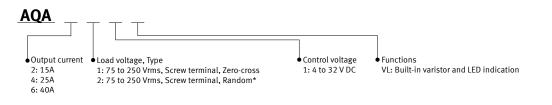


# **AQ-A** RELAYS ( AC output type )

# Load current up to Max. 40 A in the series, Small Screw Terminal SSR



#### **ORDERING INFORMATION ( PART NO. )**



\* Random type is available by custom order.

#### TYPES

#### AQ-A Solid State Relays

Туре	Load current	Load voltage	Control voltage	Part No.	Standard Packing	
	15 A			AQA211VL		
Zero-cross	25 A	75 to 250 Vrms	4 to 32 V DC	AQA411VL	Carton: 2 pcs. Case: 60 pcs.	
	40 A			AQA611VL		

Note: Random type also available. Please contact our sales representative.

#### OPTION

Тиро	Part No.	Standard Packing		
Туре	Fait NO.	Carton	Case	
Standard heat sink ( 15 A )	AQP813	5 pcs.	20 pcs.	
Standard heat sink ( 25 A )	AQP814	5 pcs.	20 pcs.	
Standard heat sink ( 40 A )	AQP815	No carton	5 pcs.	
Slim heat sink ( 45 mm wide ) ( Mountable on a DIN rail )	AQP812	No carton	8 pcs.	
DIN rail mounting plate	AQP809	No carton	50 pcs.	
Terminal cover	AQA801	No carton	50 pcs.	
Mounting rail	ATA48011	1 pcs.	100 pcs.	
Fastening plate	ATA4806	1 pcs.	200 pcs.	

#### RATING

#### ■ Ratings ( Measurement condition: at 20°C, Input ripple: 1% or less )

ltem	Part No.	AQA211VL	AQA411VL	AQA611VL	Remarks
	Control voltage				
Input side	Input current		Max. 20 mA		
	Drop–out voltage				
	Max. load current	15 A	40 A		
	Load voltage				
	Frequency				
Output side	Non-repetitive surge current	150 A	400 A	In one cycle at 60 Hz	
	"OFF–state" leakage current			at 60 Hz	
	"ON-state" voltage drop		Max. 1.6 V		at Max. carrying current
	Min. load current*		100 mA		

\* When the load current is less than the rated minimum load current, please refer to "Cautions for Use of Solid State Relays".

#### ■ Characteristics ( Measurement condition: at 20°C, Input ripple: 1% or less )

		· · · · ·								
Part No. Item	AQA211VL	AQA211VL AQA411VL AQA611VL		Remarks						
Operate time	Max.	Max. 1/2 cycle of voltage sine wave +1 ms								
Release time	Max.	1/2 cycle of voltage sine wave	+1 ms							
Insulation resistance	Min.	100 $M\Omega$ between input and o	utput	at 500 V DC						
Breakdown voltage		4,000 Vrms between input and output 2,500 Vrms between input, output and case								
Vibration resistance ( Functional )	10 to	X, Y, Z axes								
Shock resistance ( Functional )		X, Y, Z axes								
Ambient temperature		Non-icing and non- condensing								
Storage temperature		Non-icing and non- condensing								
Operational method	Ze	ro–cross ( Turn ON and Turn C	OFF)							

If the mounting surface is not metallic and a heat sink is not used,

expose the bottom surface and plate surface to improve heat dissipation.

Without external heat sink

#### **REFERENCE DATA**

1. Load current vs. ambient temperature characteristics Use load current within range specified in the figure below.

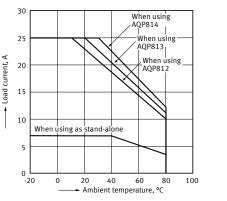
Tested condition:

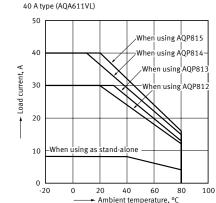
With external heat sink

When using standard heat sink (AQP815, AQP814, AQP813, AQP812)

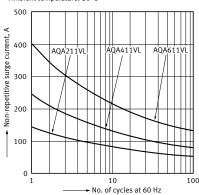
1) If attached to a heat sink, use a heat conductive compound (Ex. Momentive Performance Materials Inc. YG6111 or TSK5303) of similar coating to improve cooling.

15 A type (AQA211VL) 20 When using AQP813 or AQP812 15 Load current, A 10 When using as stand-alone 5 0 -20 0 20 40 100 60 80 °C Ambient temperature,



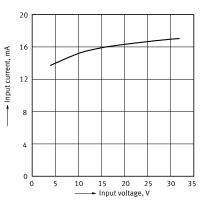


2. Non-repetitive surge current vs. carrying time characteristics\* Ambient temperature: 20°C

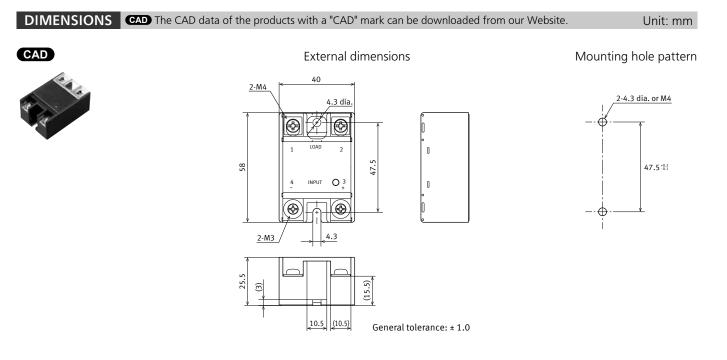


3. Input current vs. input voltage characteristics

25 A type (AQA411VL)



\* The above chart shows non-repetitive maximum rating. If a surge current is applied repeatedly, please keep it approximately 50% or less than the values shown in the above graph.



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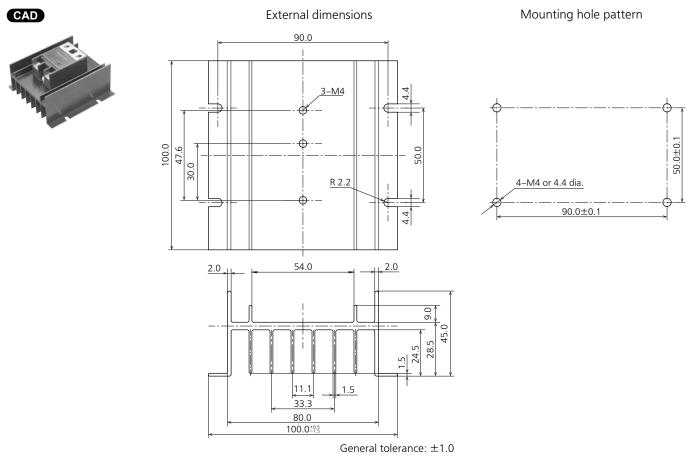
#### OPTION

CAD

#### ■ Slim heat sink (AQP812) External dimensions Mounting hole pattern 100 90 78 7-M4 40 (Effective screw depth: 6 mm) 2-4.6 dia. or M4 90 ±0.2 <u>4.6 dia.</u> ¢ 4.6×5.6 elliptical hole 30 47.6 45 78 83 1.6 "A" part

Note: When using on a DIN rail, please install so that the "A" part is on top. General tolerance: ±1.0

## Standard heat sink (AQP813)



Unit: mm

Mounting hole pattern

4-M4 or 4.4 dia.

90.0±0.1

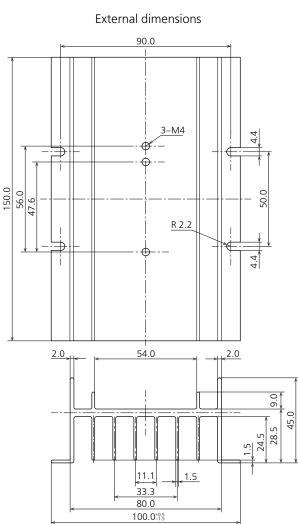
50.0±0.1

Æ

#### Standard heat sink (AQP814)









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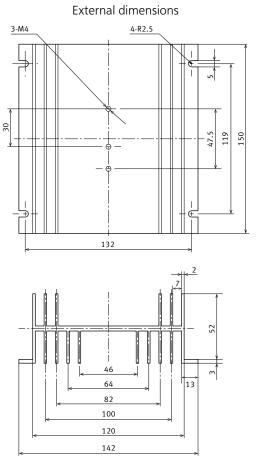
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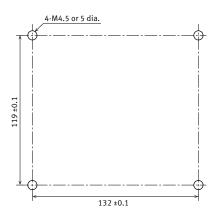
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# Solid State Relays AQ-A RELAYS ( AC output type )

#### Standard heat sink (AQP815)







Mounting hole pattern

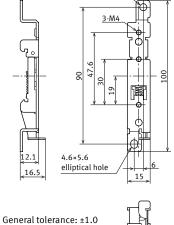
General tolerance: ±1.0

### DIN rail mounting plate ( AQP809 )

1.6





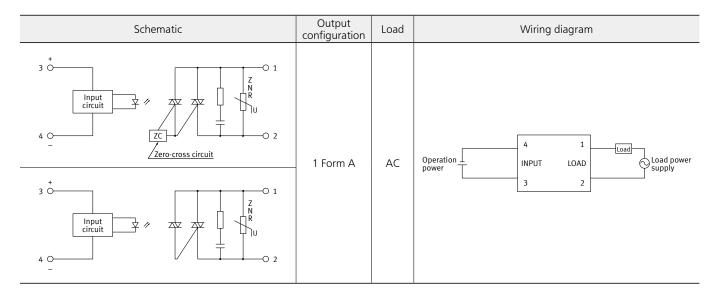


# Solid State Relays AQ-A RELAYS (AC output type)

#### Mounting rail (ATA48011) ■ Fastening plate (ATA4806) ■ Terminal cover (AQA801) CAD CAD CAD Darah a 0 External dimensions External dimensions External dimensions 1,000 ±1 50 M4 40-5.5×15 slot 2.75R 15 10 15 10 15 15 10 10.5 ATA4806 ₽E 10

Use this product as a protective terminal cover for AQ-A/SSR. It can be used for either the input or output side. General tolerance: ±1.0

#### SCHEMATIC AND WIRING DIAGRAMS



#### SAFETY STANDARDS

Туре		UL ( Recogr		CSA ( Certified )		VDE ( Certified )				
		File No. ( Standard No. )	Contact rating	File No. (Standard No.)	Contact rating	File No. ( Standard No. )	Contact rating (Reinforced insulation)	Remarks		
	15 A t		15 A type	542440	15 A 264 V AC			Nr. 40031857	15 A 250 V AC	
AQ–A ( AC output type )	AC output		E43149 (UL508, UL60950-1)			( Certified by C–UL )		25 A 250 V AC		
(AC output type)	output	40 A type (01508, 0160950-1) 40 A 26		40 A 264 V AC			(EN62368–1)	40 A 250 V AC		

Note: For the latest information on compliance with safety standards, please refer to our website.

Please refer to **"the latest product specifications"** when designing your product. • Requests to customers: https://industrial.panasonic.com/ac/e/salespolicies/

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# A SAFETY WARNINGS

- Do not use the product under conditions that exceed the range of its specifications. It may cause overheating, smoke, or fire.
- Do not touch the recharging unit while the power is on. There is a danger of electrical shock.
  Be sure to turn off the power when performing mounting,

maintenance, or repair operations on the relay (including connecting parts such as the terminal board and socket).

#### **Cautions for Use of Solid State Relays**

#### Derating design

Derating is a significant factor for reliable design and product life. Even if the conditions of use (temperature, current, voltage, etc.) of the product are within the absolute maximum ratings, reliability may be lowered remarkably when continuously used in high load conditions (high temperature, high humidity, high current, high voltage, etc.) Therefore, please derate sufficiently below the absolute maximum ratings and evaluate the device in the actual condition.

Moreover, regardless of the application, if malfunctioning can be expected to pose high risk to human life or to property, or if products are used in equipment otherwise requiring high operational safety, in addition to designing double circuits, that is, incorporating features such as a protection circuit or a redundant circuit, safety testing should also be carried out.

# Applying stress that exceeds the absolute maximum rating

If the voltage or current value for any of the terminals exceeds the absolute maximum rating, internal elements will deteriorate because of the overvoltage or overcurrent. In extreme cases, wiring may melt, or silicon P/N junctions may be destroyed.

Therefore, the circuit should be designed in such a way that the load never exceed the absolute maximum ratings, even momentarily.

#### Phototriac coupler

The phototriac coupler is designed solely to drive a triac. As a condition, the triac must be powered beforehand.

#### Unused terminals

1) Phototriac coupler

The No. 3 terminal is used with the circuit inside the device. Therefore, do not connect it to the external circuitry. (6 pins)

#### 2) AQ-H

The No. 5 terminal is connected to the gate.

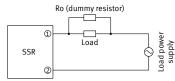
Do not directly connect No. 5 and 6 terminals.

#### Short across terminals

Do not short circuit between terminals when device is energized, since there is possibility of breaking of the internal IC.

#### When used for the load less than rated

An SSR may malfunction if it is used below the specified load. In such an event, use a dummy resistor in parallel with the load.



#### **Load Specifications**

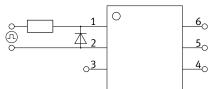
Туре	Load current
AQ-G All models	20 mA
AQ1 All models	50 mA
AQ8 All models	50 mA
AQ-J All models	50 mA
AQ-A (AC output type)	100 mA

Check the connection diagrams in the catalog and be sure to connect the terminals correctly. If the device is energized with short circuit or any wrong connection, it may cause unexpected malfunction, abnormal heat or fire.

#### Noise and surge protection at the input side 1) Phototriac coupler and AQ-H

If reverse surge voltages are present at the input terminals, connect a diode in reverse parallel across the input terminals and keep the reverse voltages below the reverse breakdown voltage. Typical circuits are below shown.

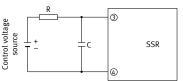
< Phototriac coupler (6-pin)>



#### 2) SSR

A high noise surge voltage applied to the SSR input circuit can cause malfunction or permanent damage to the device. If such a high surge is anticipated, use C or R noise absorber in the input circuit.

Typical circuits are below shown



#### Recommended input current of Phototriac coupler and AQ-H

Design in accordance with the recommended operating conditions for each product.

Since these conditions are affected by the operating environment, ensure conformance with all relevant specifications.

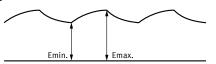
#### Ripple in the input power supply

If ripple is present in the input power supply, observe the following: 1) Current-sensitive type (Phototriac Coupler, AQ-H)

- (1) For LED forward current at Emin, please maintain the value mentioned at "Recommended input current."
- (2) Please make sure the LED forward current for Emax. is no higher than 50 mA.

#### 2) Voltage-sensitive type (AQ-G, AQ1, AQ8, AQ-J, AQ-A)

The Emin. should exceed the minimum rated control voltage
The Emax. should not exceed the maximum rated control voltage



When the input terminals are connected with reverse polarity

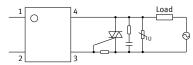
Product name	If the polarity of the input control voltage is reversed
AQ1, AQ-J, AQ-A (AC)	Reversing the polarity will not cause damage to the device, due to the presence of a protection diode, but the device will not operate.
AQ-H, AQ-G, AQ8, AQ-A (DC)	Reversing the polarity may cause permanent damage to the device. Take special care to avoid polarity reversal or use a protection diode in the input circuit.

#### Noise and surge protection at the output side 1) Phototriac coupler and AQ-H

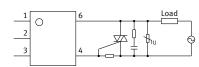
The figure below shows an ordinary triac drive circuit. Please add a snubber circuit or varistor, as noise/surge on the load side could damage the unit or cause malfunctions.

Typical circuits are shown below.

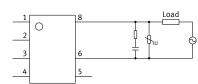
#### <Phototriac coupler SOP4 and DIP4 types>



#### <Phototriac coupler DIP6 type>



#### <AQ-H>

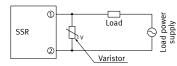


Note: Connection of an external resister, etc., to terminal No. 5 (gate) is not necessary

#### 2) SSR

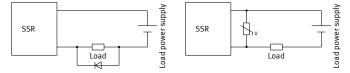
#### (1) AC output type

A high noise surge voltage applied to the SSR load circuit can cause malfunction or permanent damage to the device. If such a high surge is anticipated, use a varistor across the SSR output.



#### (2) DC output type

If an inductive load generates spike voltages which exceed the absolute maximum rating, the spike voltage must be limited. Typical circuits are shown below.



- 3) Clamp diode and snubber circuit can limit spike voltages at the load side. However, long wires may cause spike voltages due to inductance. It is recommended to keep wires as short as possible to minimize inductance.
- 4) Output terminals may become conductive although the input power is not applied, when a sudden voltage rise is applied to it even when the relay is off. This may occur even if voltage rise between terminals is less than the repetitive peak OFF-state voltage. Therefore, please perform sufficient tests with actual conditions.
- 5) When controlling loads in which the voltage and current phases differ, a sudden voltage rise is applied during turnoff, and the triac sometimes does not turn off. Please conduct sufficient tests using actual equipment.
- 6) When controlling loads using zero-cross voltage types in which the voltage and current phases differ, the triac sometimes does not turn on regardless of the input state, so please conduct sufficient tests using actual equipment.

#### Cleaning (for PC board mounting type)

Cleaning the solder flux should use the immersion washing with an organic solvent. If you have to use ultrasonic cleaning, please adopt the following conditions and check that there are no problems in the actual usage.

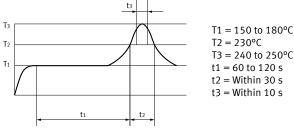
- Frequency
- : 27 to 29kHz Ultrasonic output: No greater than 0.25W/cm<sup>2</sup> (Note)
- Cleaning time : 30s or less
- Others : Float PC board and the device in the cleaning solvent to prevent from contacting the ultrasonic vibrator

Note: Applies to unit area ultrasonic output for ultrasonic baths

- Notes for mounting (for PC board mounting type) 1) When different kinds of packages are mounted on PC board, temperature rise at soldering lead is highly dependent on package size. Therefore, please set the lower temperature
  - soldering condition than the conditions of item "14. Soldering", and confirm the temperature condition of actual usage before soldering.
  - 2) When mounting condition exceeds our recommendation, the device characteristics may be adversely affected. It may occur package crack or bonding wire breaking because of thermal expansion unconformity and resin strength reduction. Please contact our sales office about the propriety of the condition.
  - 3) Please confirm the heat stress by using actual board because it may be changed by board condition or manufacturing process condition
  - 4) Solder creepage, wettability, or soldering strength will be affected by the mounting condition or used soldering type. Please check them under the actual production condition in detail.
  - 5) Please apply coating when the device returns to a room temperature.

#### Soldering

- 1) When soldering surface-mount terminals, the following conditions are recommended.
  - IR (Infrared reflow) soldering method (Recommended condition reflow: Max. 2 times, measurement point: soldering lead)



(2) Other soldering methods

Other soldering methods (VPS, hot-air, hot plate, laser heating, pulse heater, etc.) affect the relay characteristics differently, please evaluate the device under the actual usage.

#### (3) Soldering iron method

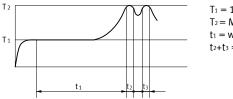
Tip temperature: 350 to 400 °C Wattage : 30 to 60 W

Soldering time : within 3 s

# 2) When soldering standard PC board terminals, the following conditions are recommended.

(1) DWS soldering method

(Recommended condition number of times: Max. 1 time, measurement point: soldering lead \*1)



 $T_1 = 120^{\circ}C$   $T_2 = Max. 260^{\circ}C$   $t_1 = within 60 s$  $t_2+t_3 = within 5 s$ 

\*1 Solder temperature: Max. 260 °C

(2) Other dip soldering method (recommended condition: 1 time) Preheating: Max. 120 °C, within 120 s,

measurement point:

soldering lead Soldering: Max. 260 °C, within 5 s\*, measurement area: soldering temperature \*Phototriac coupler and AQ-H: within 10 s

(3) Manual soldering method Tip temperature: 350 to 400°C Wattage: 30 to 60 W Soldering time: within 3 s

• We recommend one with an alloy composition of Sn3.0Ag0.5Cu. • Others

- 1) If an SSR is used in close proximity to another SSR or heat-generating device, its ambient temperature may exceed the allowable level. Carefully plan SSR layout and ventilation.
- 2) Terminal connections should be made by referring to the associated wiring diagram.
- 3) For higher reliability, check device quality under actual operating conditions.
- 4) To prevent the danger of electrocution, turn off the power supply when performing maintenance. Although AQ-A (DC output type) is constructed with insulation for the input/ output terminals and the rear aluminum plate, the insulation between the input/output and the rear aluminum plate is not UL approved.

- Transportation and storage
  - 1) Extreme vibration during transport may deform the lead or damage the device characteristics. Please handle the outer and inner boxes with care.
  - 2) Inadequate storage condition may degrade soldering, appearance, and characteristics. The following storage conditions are recommended:
    - Temperature: 0 to 45 °C
    - Humidity: Max. 70%RH
    - Atmosphere: No harmful gasses such as sulfurous acid gas, minimal dust.

#### 3) Storage of Phototriac coupler (SOP type)

In case the heat stress of soldering is applied to the device which absorbs moisture inside of its package, the evaporation of the moisture increases the pressure inside the package and it may cause the package blister or crack. This device is sensitive to moisture and it is packed in the sealed moisture-proof package. Please make sure the following condition after unsealing.

- Please use the device immediately after unsealing. (Within 30 days at 0 to 45 °C and Max. 70%RH)
- If the device will be kept for a long time after unsealing, please store in the another moisture-proof package containing silica gel. (Please use within 90 days.)

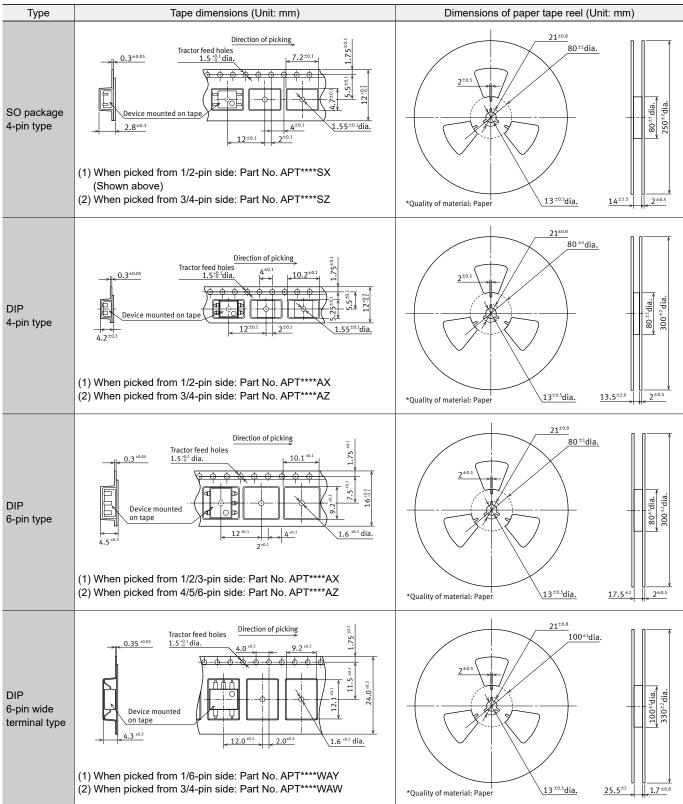
#### Water condensation

Water condensation occurs when the ambient temperature changes suddenly from a high temperature to low temperature at high humidity, or the device is suddenly transferred from a low ambient temperature to a high temperature and humidity. Condensation causes the failures such as insulation deterioration. Panasonic Industry Co., Ltd. does not guarantee the failures caused by water condensation.

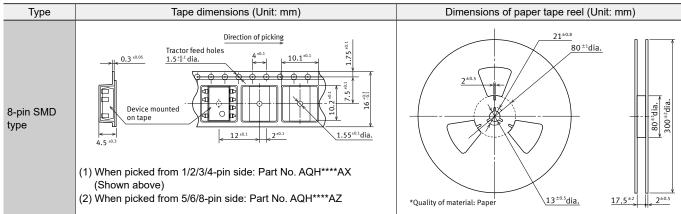
The heat conduction by the equipment the SSR is mounted may accelerate the water condensation. Please confirm that there is no condensation in the worst condition of the actual usage. (Special attention should be paid when high temperature heating parts are close to the SSR.)

#### The following shows the packaging format

#### 1) Tape and reel (Phototriac coupler)



#### 2) Tape and reel (AQ-H)



#### 3) Tube

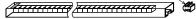
Phototriac coupler and AQ-H SSR are packaged in a tube as pin No. 1 is on the stopper B side. Observe correct orientation when mounting them on PC boards.

<Phototriac coupler SOP type>



<Phototriac coupler DIP type and AQ-H SSR>





#### Snubber Circuit

#### Reduce dv/dt

An SSR used with an inductive load can accidentally fire due to a high load voltage rise rate (dv/dt), even though the load voltage is below the allowable level (inductive load firing).

Our SSRs contain a snubber circuit designed to reduce dv/dt (except AQ-H).

#### Selecting the snubber constants

#### 1) C selection

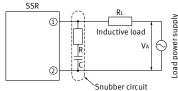
The charging coefficient tau for C of the SSR circuit is shown in formula ①

τ =(RL+R) × C ------①

By setting formula (1) so that it is below dv/dt value you have: C=0.632V<sub>A</sub>/[(dv/dt) (R<sub>L</sub>+R)] -----②

By setting C = 0.1 to 0.2 µF, dv/dt can be controlled to between nV/µs and n+V/µs or lower. For the condenser, use either an MP condenser metallized polyester film. For the 100 V line, use a voltage between 250 and 400 V, and for the 200 V line, use a voltage between 400 and 600 V.

2) R selection



#### Thermal Design

SSRs used in high-reliability equipment require careful thermal design. In particular, junction temperature control has a significant effect on device function and life time. The rated load current for PC boardmounting SSRs is defined as the maximum current allowable at an ambient temperature of 40 °C (30 °C) and under natural cooling. If the ambient temperature exceeds the SSRs derating temperature point [40 °C (30 °C)], load current derating in accordance with the load current vs temperature diagram becomes necessary. If adjacent devices act as heat sources, the SSR should be located more than 10 mm away from those devices.

SSRs with a 5 A rating or more must be used with the dedicated heat sinks listed in Table 1 or equivalents. To ensure adequate thermal conduction, apply thermal conductive compound (Ex. Momentive Performance Materials Inc. YG6111 or TSK5303) to the SSR's mounting surface. For information on external heat sinks for our SSRs and their mounting method, refer to "Data and Cautions for Use for respective relay".

If there is no resistance R (the resistance R controls the discharge current from condenser C), at turn-on of the SSR, there will be a sharp rise in dv/dt and the high peak value discharge current will begin to flow

This may cause damage to the internal elements of the SSR. Therefore, it is always necessary to insert a resistance R. In normal applications, for the 100 V line, have R = 10 to 100  $\Omega$  and for the 200 V line, have R = 20 to 100  $\Omega$ . (The allowable discharge current at turn on will differ depending on the internal elements of the SSR.) The power loss from R, written as P, caused by the discharge current and charging current from C, is shown in formula (3) below. For the 100 V line, use a power of 1/2 W, and for the 200 V line, use a power above 2 W.

$$P = \frac{C \times V_{A^2} \times f}{2} \dots \dots \dots 3$$
  
f=Power supply frequency

Also, at turn-off of the SSR, a ringing circuit is formed with the capacitor C and the circuit inductance L, and a spike voltage is generated at both terminals of the SSR. The resistance R serves as a control resistance to prevent this ringing. Moreover, a good non-inductive resistance for R is required. Carbon film resistors or metal film resistors are often used.

For general applications, the recommended values are C = 0.1  $\mu$ F and R = 20 to 100  $\Omega$ . There are cases of resonance in the inductive load, so the appropriate care must be taken when making your selections.

#### Table 1 Dedicated on-board heat sinks

Туре	Heat sink	Load current
AQ10A2-ZT4/32VDC	AQ1802	10A
	AQP810*	
AQ-J (10A)	AQP813	10A
	AQP812*	
	AQP810*	
AQ-J (15A)	AQP813	15A
	AQP812*	
	AQP810*	
	AQP813	20A
AQ-J (25A)	AQP812*	
	AQP815	25A
	AQP813	15A
AQ-A (15A)	AQP812*	IJA
	AQP814	
AQ-A (25A)	AQP813	25A
	AQP812*	
	AQP813	30A
	AQP812*	30A
AQ-A (40A)	AQP814	40A
	AQP815	40A
	AQP812*	8A
AQ-A DC (10A)	AQP815	10A
AQ-A DC (30A)	AQP812*	30A

\* It is possible to mounting on the DIN rail

#### **Protection Circuit**

High-reliability SSR circuits require an adequate protection circuit, as well as careful study of the characteristics and maximum ratings of the device.

#### Over-Voltage Protection

The SSR load power supply requires adequate protection against over-voltage errors from various causes. The methods of overvoltage protection include the following:

1) Use devices with a guaranteed reverse surge withstand voltage

(controlled avalanche devices, etc.)

#### Choosing the rated voltage of the ZNR

(1) Peak supply voltage

(2) Supply voltage variation

(3) Degradation of ZNR characteristic (1 mA ±10%)

#### Example of ZNR (Panasonic Industry Co., Ltd. )

#### 2) Suppress transient spikes

Use a switching device in the secondary circuit of a transformer or use a switch with a slow opening speed.

#### 3) Use a surge absorption circuit

Use a CR surge absorber or varistor across the load power supply or SSR.

Special care must be taken so power on/off surges or external surges do not exceed the device's rated load voltage. If a surge voltage exceeding the device's rated voltage is anticipated, use a surge absorption device and circuit (e.g. a ZNR from Panasonic Industry Co., Ltd. ).

#### (4) Tolerance of rated voltage (±10%)

For application to 100 V AC lines, choose a ZNR with the following rated voltage:

 $(1) \times (2) \times (3) \times (4) = (100 \times \sqrt{2}) \times 1.1 \times 1.1 \times 1.1 = 188$  (V)

Varistor Types voltage	Varistor	r Max. allov		Max.	Max. x. average	Withstanding energy		Withstanding surge current		Electrostatic			
				control voltage	pulse electric power	(10/1000µs)	(2ms)	1time	(8/20µs) 2time	capacitance (Reference)			
	V1mA (V)	ACrms (V)	DC (V)	V50A (V)	(W)	(J)	(J)	(A)	(A)	@1KHz (pF)			
ERZV14D201	200 (185 to 225)	130	170	340	0.6	70	50	6,000	5,000	770	-		
ERZV14D221	220 (198 to 242)	140	180	360	0.6	78	55	6,000	5,000	740	- I. D. I.	.T.,	
ERZV14D241	240 (216 to 264)	150	200	395	0.6	84	60	6,000	5,000	700			
ERZV14D271	270 (247 to 303)	175	225	455	0.6	99	70	6,000	5,000	640		$\left( \right)$	
ERZV14D361	360 (324 to 396)	230	300	595	0.6	130	90	6,000	4,500	540			
ERZV14D391	390 (351 to 429)	250	320	650	0.6	140	100	6,000	4,500	500	0.8 dia.		
ERZV14D431	430 (387 to 473)	275	350	710	0.6	155	110	6,000	4,500	450		20 min	
ERZV14D471	470 (423 to 517)	300	385	775	0.6	175	125	6,000	4,500	400			D : 17.5 dia. max. T : 6.5 max.
ERZV14D621	620 (558 to 682)	385	505	1,025	0.6	190	136	5,000	4,500	330	- U U	UU↓	H : 20.5 max. W: 7.5 ±1
ERZV14D681	680 (612 to 748)	420	560	1,120	0.6	190	136	5,000	4,500	320	- → <del>   ~</del> –	• <del>  &lt;−</del> L	(Unit: mm)

#### Over-Current Protection

An SSR circuit operated without overcurrent protection may result in damage to the device. Design the circuit so the device's rated junction temperature is not exceeded for a continuous overload current. (e.g. Surge current into a motor or light bulb)

The surge-on current rating applies to over-current errors which occur less than several tens of times during the service life of a

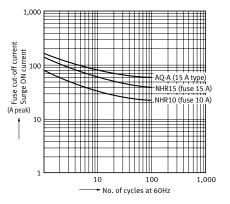
semiconductor device. A protection coordination device is required for this rating.

Methods of over-current protection include the following:

- 1) Suppressing over-currents
- Use a current limiting reactor in series with the load power supply. 2) Use a current shut-off device

Use a current limiting fuse or circuit breaker in series with the load power supply.

# Example of executing fuse selection of over-current protection cooperation



#### Load Type Description

#### Heaters (Resistive load)

The SSR is best suited to resistive loads. Noise levels can be drastically lowered with zero-crossing switching.

#### Lamps

Tungsten or halogen lamps draw a high inrush current when turned on (approximately 7 to 8 times the steady state current for zerocrossing SSRs; approximately 9 to 12 times, in the worst case, for random type SSRs). Choose an SSR so the peak of the inrush current does not exceed 50% of the SSR surgeon current.

#### Motors load

When starting, an electric motor draws a symmetrical AC starting current some 5 to 8 times the steady-state load current,

superimposed on a DC current. The starting time during which this high starting current is sustained depends on the capacities of the load and load power supply. Measure the starting current and time under the motor's actual operating conditions and choose an SSR so the peak of the starting current does not exceed 50% of the SSR surge-on current.

When the motor load is deactivated, a voltage exceeding the load supply voltage is applied to the SSR due to counter-EMF.

This voltage is approximately 1.3 times the load supply voltage for induction motors, and approximately 2 times that for synchronous motors.

#### Reversible motor control

When the direction of motor rotation is reversed, the transient current and time required for the reversal far exceed those required for simple starting. The reversing current and time should also be measured under actual operating conditions.

For a capacitor-starting, single-phase induction motor, a

capacitive discharge current appears during the reversal process. Be sure to use a current limiting resistor or reactor in series with the SSR.

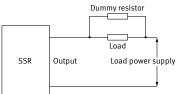
Also, the SSR should have a high marginal voltage rating, since a voltage twice as high as the load supply voltage develops across the SSR in the reversal process.

For reversible motor control, carefully design the driver circuit so the forward and reverse SSRs do not turn on at the same time.

#### Solenoids

AC-driven solenoid contactors or solenoid valves also draw inrush current when they are activated. Choose an SSR such that the peak of the inrush current does not exceed 50% of the SSR surgeon current. For small solenoid valves and AC relays in particular, a leakage current may cause the load to malfunction after the SSR turns off. In such an event, use a dummy resistor in parallel with the load.

#### Using an SSR below the specified load



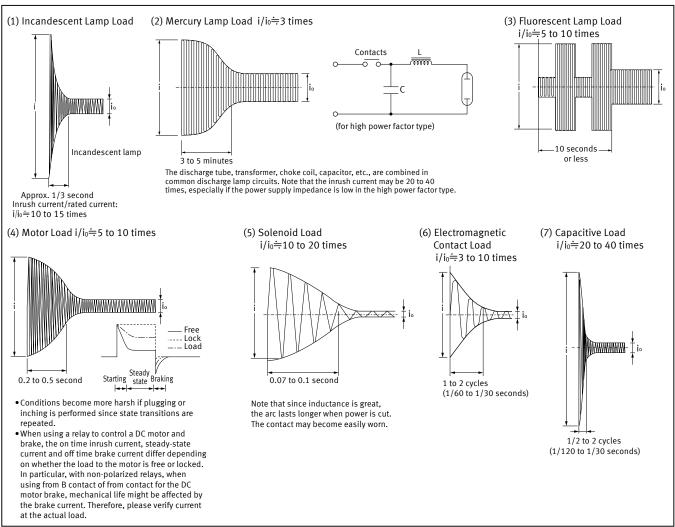
#### Capacitive load

A capacitive load (switching regulator, etc.) draws an inrush current to charge the load capacitor when the SSR turns on. Choose an SSR so the peak of the inrush current does not exceed 50% of the SSR surge-on current. A timing error of up to one cycle can occur when a switch used in series with the SSR is opened or closed. If this is a problem, use an inductor (200 to 500  $\mu$ H) in series to the SSR to suppress dv/dt error.

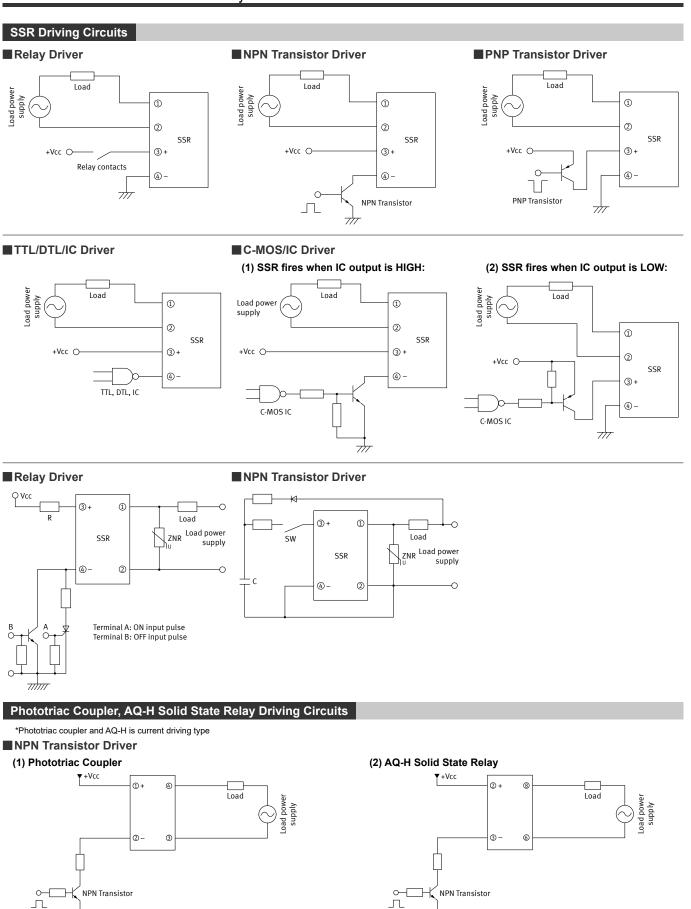
#### Other electronic equipment

In general, electronic equipment uses line filters in the primary supply circuit.

The capacitors used in the line filters may cause the SSR to malfunction due to dv/dt turn on when the equipment is turned on or off. In such an event, use an inductor (200 to 500  $\mu$ H) in series with the SSR to suppress dv/dt turn on.



#### Load Inrush Current Wave and Time



Please refer to **"the latest product specifications"** when designing your product. •Requests to customers: https://industrial.panasonic.com/ac/e/salespolicies/

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