#### AC-DC Power Supplies Bus Converter · Power Module Type















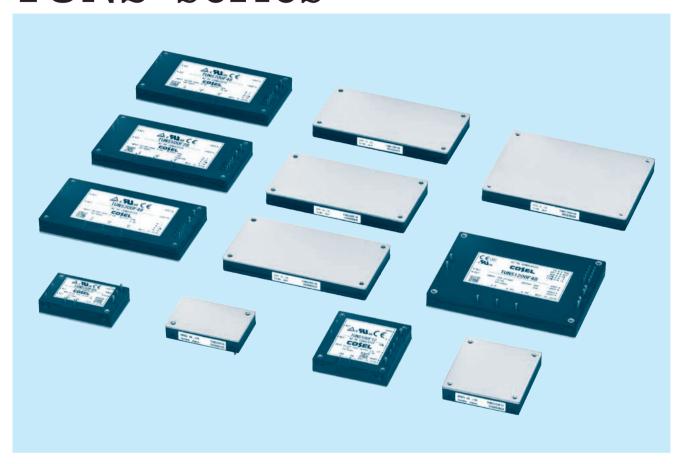








# **TUNS-series**



#### Feature

AC-DC Power Module Type Converter

Harmonic attenuator (Complies with IEC61000-3-2 class A)

Thin and small size

Built-in overcurrent, overvoltage and thermal protection circuits

Mounting hole (M3 tapped)

<TUNS50F/100F/300F/500F/700F>

Universal input 85 - 264VAC

Peak current (TUNS500F)

<TUNS1200F>

Wide input 85 - 305VAC

For medical electric equipment

Constant current regulation

Output voltage can be varied to near 0V

Parallel operation possible

#### CE marking

Low voltage directive RoHS Directive

### UKCA marking

Electrical Equipment Safety Regulations RoHS Regulations

### Safety Approval

UL60950-1, C-UL, EN62368-1 (TUNS50F/100F/300F/500F/700F) UL62368-1, C-UL, EN62368-1 (TUNS1200F) ANSI/AAMI ES60601-1, EN60601-1 3rd (TUNS1200F)

#### **■** 5-year warranty

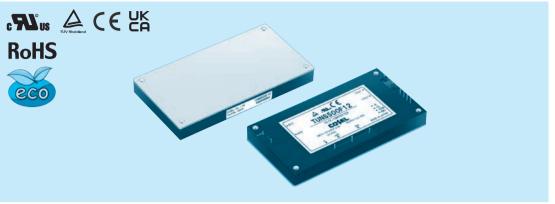
## Optional parts

Heat sink

#### Ordering information

# **TUNS500F**

500 F



- Series name
   Single output
   Output wattage
- 4 Universal Input
- ⑤Output voltage
- Optional
   T : with Mounting hole  $(\phi 3.4 \text{ thru})$ 
  - Y1: Outputvoltage adjustment
  - range ±20% (Only 48V) R1: with Remote ON/OFF
  - (Negative logic control) R2: with Remote ON/OFF (Negative logic and Low standby power)
- R3: with Remote ON/OFF (Positive logic control)
- N1: Auto restart from thermal protection

- \*Avoid short circuit between +BC/R and -BC. It may cause the failure of inside components.
- \*Keep TRM open, if output voltage adjustment is not necessary.
- \*If remote sensing is not necessary, connect between +Vout & +S and between -Vout & -S.

MODEL	TUNS500F12	TUNS500F28	TUNS500F48	
MAX OUTPUT WATTAGE[W]	504	504	504	
DC OUTPUT	12V 42A (Peak 55A)	28V 18A (Peak 24A)	48V 10.5A (Peak 14A)	

#### **SPECIFICATIONS**

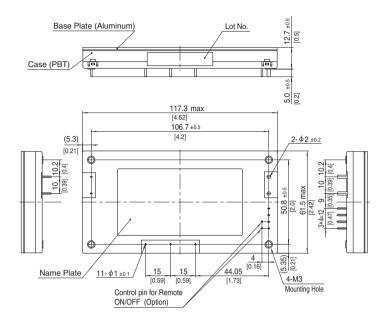
	MODEL		TUNS500F12	TUNS500F28	TUNS500F48				
	VOLTAGE[V]		AC85 - 264 1 $\phi$						
	CHRRENIIVI		6.0typ (lo=100%)						
			V 3.0typ (lo=100%)						
INPUT	FREQUENCY[Hz]		50/60 (47 - 63)						
	EEEIOIENOV(0/1	ACIN 100V	84typ	87typ	88typ				
	EFFICIENCY[%]	ACIN 200V	86typ	90typ	90.5typ				
	DOWER	ACIN 100V	0.96typ	<u> </u>					
	POWER FACTOR (Io=100%)	ACIN 200V	0.93typ						
	INRUSH CURRENT		Limited by external resistance						
	LEAKAGE CURREN	Γ[mA]	0.75max (ACIN 240V 60Hz, lo=100%, According to IEC62368-1)						
	VOLTAGE[V]		12	28	48				
	CURRENT[A]	*3	42 (Peak 55)	18 (Peak 24)	10.5 (Peak 14)				
	LINE REGULATION[	mV]	24max	56max	96max				
	LOAD REGULATION	[mV]	24max	56max	96max				
	RIPPLE[mVp-p]	0 to +100℃*1	120max	180max	250max				
	KIPPLE[IIIVP-P]	-40 to 0°C *1	150max	200max	300max				
OUTPUT	RIPPLE NOISE[mVp-p]	0 to +100°C <b>*</b> 1	150max	200max	300max				
OUIFUI	HIFFEE NOISE[IIIVP-P]	-40 to 0°C *1	200max	300max	450max				
	TEMPERATURE REGULATION[mV]	0 to +65℃	120max	280max	480max				
	TEMPERATURE REGULATION[IIV]	-40 to +100°C	240max	560max	960max				
	DRIFT[mV] *2		40max	90max	180max				
	OUTPUT VOLTAGE ADJUSTMEN	T DANGEIVI	Fixed (TRM pin open), adjustable by external resistor or external signal						
	OUTFUT VOLIAGE ADJUSTMEN	II NANGE[V]	9.60 - 14.40	22.40 - 33.60	38.40 - 52.80 (-Y1 Option : 38.4 - 57.6)				
	OUTPUT VOLTAGE SETTING[V]		11.91 - 12.29	27.56 - 28.44	47.24 - 48.76				
DDOTECTION	OVERCURRENT PROT	ECTION	Works over 101% of peak current and recovers automatically						
PROTECTION CIRCUIT AND	OVERVOLTAGE PROTECTION[V]		15.00 - 16.80	35.00 - 39.20	55.20 - 64.80 (-Y1 Option : 60.0 - 67.2)				
OTHERS	REMOTE SENSING		Provided						
	REMOTE ON/OFF		Optional (External power supply is required)						
	INPUT-OUTPUT · RC *5		AC3,000V 1minute, Cutoff current = 10mA, DC500V 50M $\Omega$ min (20±15 $^{\circ}$ C)						
ISOLATION	INPUT-FG		AC2,000V 1minute, Cutoff current = 10mA, DC500V 50M $\Omega$ min (20±15 $^{\circ}$ C)						
IOOLATION	OUTPUT · RC-FG *5		AC500V 1minute, Cutoff current = 100mA, DC500V 50M $\Omega$ min (20±15 $^{\circ}$ C)						
	OUTPUT-RC *5		AC100V 1minute, Cutoff current = 100mA, DC100V 10M $\Omega$ min (20±15 $^{\circ}$ C)						
	OPERATING TEMP., HUMID. AND ALTITUDE								
ENVIRONMENT	STORAGE TEMP., HUMID. AND ALTITUDE		-40 to +100°C, 20 - 95%RH (Non condensing), 9,000m (30,000 feet) max						
LITTIIOITIMENT	VIBRATION		10 - 55Hz, 49.0m/s² (5G), 3minutes period, 60minutes each along X, Y and Z axis						
	IMPACT		196.1m/s² (20G), 11ms, once each along X, Y and Z axis						
SAFETY AND	AGENCY APPROVALS UL60950-1, C-UL (CSA60950-1), EN62368-1								
NOISE REGULATIONS	HARMONIC ATTENU	ATOR	Complies with IEC61000-3-2 (Class A) *4						
OTHERS	CASE SIZE/WEIGHT		117.3×12.7×61.5mm [4.62×0.5×2.42 inches] (W×H×D) / 190g max						
UTILLIO	COOLING METHOD		Conduction cooling (e.g. heat radiation from the aluminum base plate to the attached heat sink)						

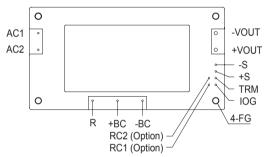
- Refer to instruction manual for measuring method of electric characteristics.
- Drift is the change in DC output for an eight hour period after a half-hour warm-up at 25°C, with the input voltage held constant at the rated input/output.
- ( ) means peak current. Avoid operating with peak current continuously. It may cause failure of the components inside the product. There are limitation of available condition of the peak current, such as peak time, duty etc. (Refer to the instruction manual in detail.)
- Please contact us about another class.
- "RC" is applicable when remote control (optional) is added.

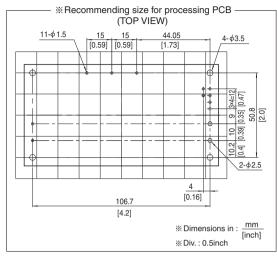




#### **External view**



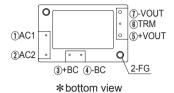




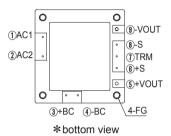
- \*\* Tolerance : ±0.3 [± 0.012]
- \* Weight : 190g max
- ※ Dimensions in mm, [ ]=inches
- Mounting hole screwing torque: 0.49N · m (5.0kgf · cm) max

#### Pin Configuration

#### TUNS50F

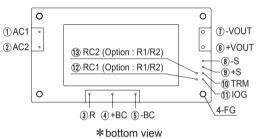


#### TUNS100F

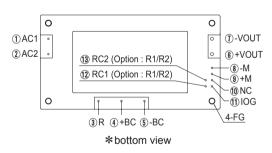


#### No. Pin Connection Function AC1 AC input 2 (2) AC2 3 3 +BC +BC output 4 -BC -BC output 4 +VOUT +DC output (5) (5) -DC output 7 9 -VOUT -S Remote sensing (-) 8 Remote sensing (+) **(6)** +S **6** (7) TRM Adjustment of output voltage FG Mounting hole (FG)

#### TUNS300F/TUNS500F/TUNS700F



#### ■ TUNS700F□□-P (OPTION)

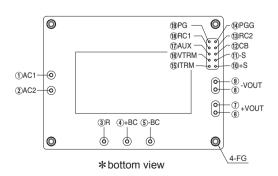


No.	Pin Connection	Function				
1	AC1	AC input				
2	AC2	AC Input				
3	R	External resistor for inrush current protection				
4	+BC	+BC output				
5	-BC	-BC output				
6	+VOUT	+DC output				
7	-VOUT	-DC output				
8	-S	Remote sensing (-)				
9	+S	Remote sensing (+)				
10	TRM	Adjustment of output voltage				
11)	IOG	Inverter operation monitor				
12	RC1	Pomoto ON/OFF (Ontion)				
13	RC2	Remote ON/OFF (Option)				
_	FG	Mounting hole (FG)				

No.	Pin Connection	Function			
8	-M	Output voltage maniter terminal			
9	+M	Output voltage monitor terminal			
10	NC	No connection			

Other than the above are the same as standard products.

#### TUNS1200F



	1					
No.	Pin	Function				
	Connection	1 dilotion				
1	AC1	AC input				
2	AC2	AC Input				
3	R	External resistor for inrush current protection				
4	+BC	+BC output				
5	-BC	-BC output				
67	+VOUT	+DC output				
89	-VOUT	-DC output				
10	+S	Remote sensing (+)				
11)	-S	Remote sensing (-)				
12	CB	Current balance				
13	RC2	Remote ON/OFF ground				
14)	PGG	Power good output ground				
15)	ITRM	Adjustment of output current				
16	VTRM	Adjustment of output voltage				
17)	AUX	Auxiliary output				
18	RC1	Remote ON/OFF				
19	PG	Power good output				
_	FG	Mounting hole (FG)				



#### Implementation • Mounting Method

#### Mounting method

- ■Use with the conduction cooling (e.g. heat dissipation from the aluminum base plate to the attached heat sink).
- ■Use a heat sink that larger than the power supply and has a large thickness so that the alminum base plate can be cooled uniformly.
- ■The unit can be mounted in any direction. When two or more power supplies are used side by side, position them with proper intervals to allow enough air ventilation. Aluminum base plate temperature of each power supply should not exceed the temperature range shown in
- ■Avoid placing the AC input line pattern layout underneath the unit. It will increase the line conducted noise. Make sure to leave an ample distance between the line pattern layout and the unit. Also avoid placing the DC output line pattern underneath the unit because it may increase the output noise. Lay out the pattern away from the unit.
- ■Avoid placing the signal line pattern layout underneath the unit because the power supply might become unstable. Lay out the pattern away from the unit.
- ■High-frequency noise radiates directly from the unit to the atmosphere. Therefore, design the shield pattern on the printed circuit board and connect it to FG or -BC. The shield pattern prevents noise radiation.
- ■When a heat sink cannot be fixed on the base plate side, order the power module with "-T"option. A heat sink can be mounted by affixing a M3 tap on the heat sink. Please make sure a mounting hole will be connected to a grounding capacitor CY.

	Mounting hole				
Standard	M3 tapped				
Optional : -T	φ3.4 thru				

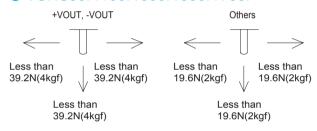
#### Stress onto the pins

- ■When too much stress is applied to the pins may damage internal connections. Avoid applying stress in excess of that shown in right figure.
- ■The pins are soldered onto the internal PCB. Therefore, Do not bend or pull the leads with excessive force.
- ■Mounting hole diameter of PCB should be 3.5mm to reduce the stress to the pins.
- ■Fix the unit on PCB (fixing fittings) by screws to reduce the stress to the pins. Be sure to mount the unit first, then solder the unit.

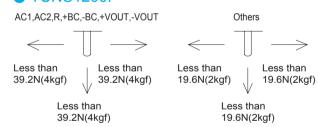
#### Soldering temperature

■Flow soldering : 260°C for up to 15 seconds. ■Soldering iron (26W) : 450°C for up to 5 seconds.

#### TUNS50F/100F/300F/500F/700F



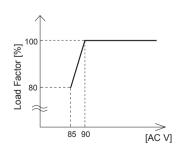
#### TUNS1200F



#### **Derating**

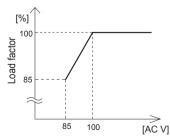
#### Input voltage derating curve

#### TUNS50F/100F



#### TUNS700F/1200F

\*TUNS1200F12 has no input voltage derating.



#### TUNS300F/500F

\*TUNS300F/500F has no input voltage derating.

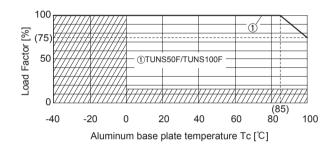
#### Derating

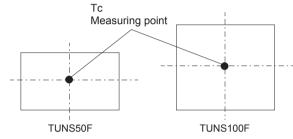
#### Output voltage derating curve

- ■Use the power modules with conduction cooling (e.g. heat dissipation from the aluminum base plate to the attached heat sink).

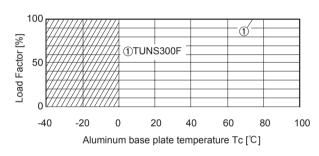
  Below shows the derating curves with respect to the aluminum base plate temperature. Note that operation within the hatched areas will cause a significant level of ripple and ripple noise.
- ■Please measure the temperature on the aluminum base plate edge side when you cannot measure the temperature of the center part of the aluminum base plate. In this case, please take 5deg temperature margin from the derating characteristics shown in below. Please reduce the temperature fluctuation range as much as possible when the up and down of the temperature are frequently generated. Contact us for more information on cooling methods.

#### TUNS50F/100F

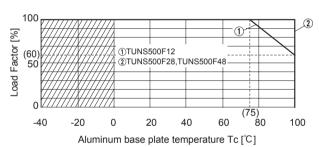




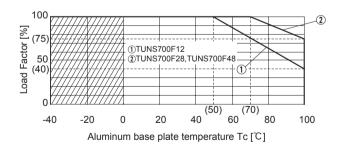
#### TUNS300F

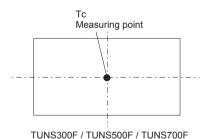


#### TUNS500F

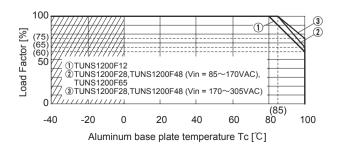


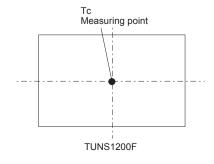
#### TUNS700F





#### TUNS1200F







#### **Instruction Manual**

◆ It is neccessary to read the "Instruction Manual" and "Before using our product" before you use our product.

https://www.cosel.co.jp/redirect/catalog/en/TUNS/ Instruction Manual Before using our product https://en.cosel.co.jp/technical/caution/index.html





#### **Basic Characteristics Data**

Model	Circuit method	frequency c	Input	Inrush current protection circuit	PCB/Pattern			Series/Parallel operation availability	
Model			current [A] <b>*</b> 1		Material	Single sided	Double sided	Series operation	Parallel operation
TUNS50F	Active filter	80-600	0.67	Thermistor	Aluminum	Yes		Yes	*2
	Flyback converter	100-300	0.67						
TUNS100F	Active filter	80-600	1.3	Thermistor	Aluminum	Yes		Yes	*2
	Forward converter	300							
TUNS300F	Active filter	100	3.6	SCR	Aluminum	Yes		Yes	*2
	Half-bridge converter	400							
TUNS500F	Active filter	100	6.0	SCR	Aluminum	Yes		Yes	*2
	Half-bridge converter	400							
TUNS700F	Active filter	100	8.6	SCR	Aluminum	Yes		Yes	*2
	Half-bridge converter	400							
TUNS1200F	Active filter	100	14	SCR	Aluminum	Yes		Yes	Yes
	Full-bridge converter	400							

<sup>\*1</sup> The value of input current is at ACIN 100V and rated load.

<sup>\*2</sup> Refer to instruction manual.